

subTerranean Haptic INvestiGator

H2020-ICT-2017-1

Grant agreement no: 780883

DELIVERABLE 7.1

Launch of project website, social media, and video channel

Due date: month 3 (March 2018)

Deliverable type: O

Lead beneficiary: PUT

Dissemination Level: PUBLIC

Main author: Krzysztof Walas

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1 Introduction

This document reports the launch of project website, social media and video channel. This activity has been carried out within Task 7.1, the description thereof is reported in the following.

Task 7.1 - Dissemination and Exploitation of Results

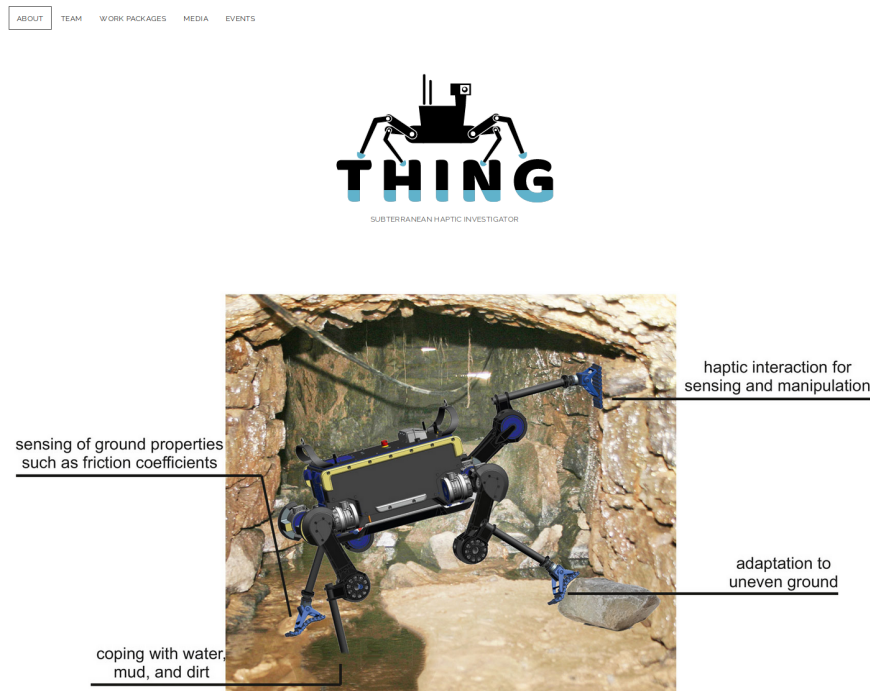
Task T7.1: Dissemination and Exploitation of Results (M9-M39) Leader: PUT. Contributors: UEDIN This task is dedicated to propagate the results of the project to other research fields, industry and to the public. We will:

- provide the robotics community with open software and contribute to the development of the ROS ecosystem
- disseminate the results regarding robotic inspection to mining and minerals processing researchers
- organize events such as workshops, tutorials, exhibitions throughout the project
- supply on-line resources (web page, social media, video channel and git repository)
- maintain contacts with media
- attend trade fairs to demonstrate the state of the robot development and gain industrial connection

In the following sections the launch of each media will be described.

2 Website

The website was launched in month 3 of the project. The domain <http://thing-h2020.eu/> was registered and the webpage is hosted on the servers of Poznan University of Technology. The layout of the site is shown in Figure 2. The webpage consists of main page, team description, workpackage explanation, media coverage and events section.



subTerraanean Haptic INvestiGator – THING

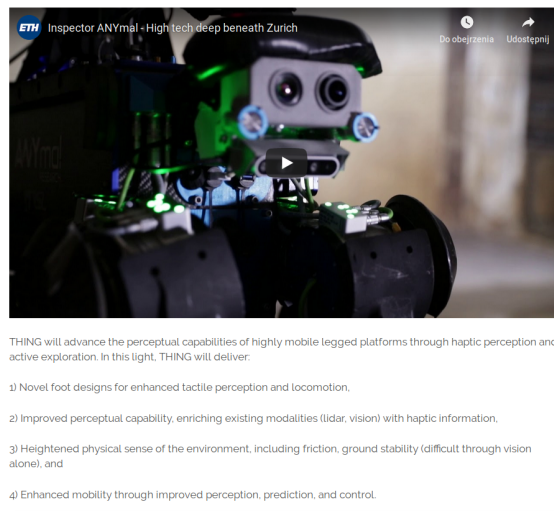


Figure 1: THING website layout.

3 Social Media

The Twitter account @THING-H2020 for the project was launched in January 2018. The videos of the consortium partners are posted at Youtube.



Figure 2: THING Twitter account.